

Best Quadratic unbiased Estimator for Variance Component of One-Way Repeated Measurement Model

Abdulhussein Saber AL-Mouel¹ and Jasim Mohammed Ali Al-Isawi²

1st: Mathematics Department, College of Education for Pure Science AL-Basrah University-Iraq

abdulhusseinsaber@yahoo.com

2nd: Mathematics Department, College of Education for Pure Science AL-Basrah University-Iraq

Jas77im@gmail.com

ABSTRACT

The studies of analysis of variance components is one of the important topics in mathematical statistics for this subject of wide application. In this paper given best quadratic unbiased estimator of variance components for balanced data for linear one-way repeated measurement model (RMM). We computed the quadratic unbiased estimator, which has minimum variance (best quadratic unbiased estimate (BQUE)) by using analysis of variance (ANOVA) method of estimating the variance components.

Indexing terms/Keywords: Quadratic Estimator, Repeated Measurement Model, ANOVA Method, Variance Components, Quadratic Form, Estimation.

Language: English

Date of Submission: 2018-04-13

Date of Acceptance: 2018-04-20

Date of Publication: 2018-04-30

ISSN: 2347-1921

Volume: 14 Issue: 01

Journal: Journal of Advances in Mathematics

Website: https://cirworld.com



This work is licensed under a Creative Commons Attribution 4.0 International License.

1. INTRODUCTION

The variance component analogue of the best linear unbiased estimator of a function of effects is a best quadratic unbiased estimator (BQUE), that is, a quadratic function of the observations that is unbiased for the variance component and has minimum variance among all such estimators [8].

Repeated measurements is a term used to describe data in which the response variable for each experimental unit is observed on multiple occasions and possibly under different experimental conditions. There are variety of disciplines, which make use of repeated measurements as applications in the health and life sciences, epidemiology, biomedical research, education, psychology and the social sciences, etc. Repeated measurements



occur frequently in observational studies, which are longitudinal in nature, and in experimental studies incorporating repeated measures designs. In the repeated measurements setting, independent factors or covariates may be classified into one of two categories: within-subject covariates and between-subject covariates. Within-subject covariates, also referred to as within-subject or within-unit factors, repeated measures factors and/or time-dependent covariates, represent variables or experimental conditions which vary over time within subjects or experimental units [9].

Several methods are available in literature for estimating the variance components. In this paper, we consider analysis of variance methods of estimating the variance components linear of the one-way repeated measurement model (RMM) to obtained BQUE for this model.

2. SETTING THE MODEL

Consider the linear model and parameterization for the one-way (RMM) with one between – units factor incorporating univariate random effects [1].

$$Y_{ijk} = \mu + \tau_j + \delta_{i(j)} + \gamma_k + (\tau \gamma)_{jk} + \varepsilon_{ijk}$$
 (1)

where

i = 1, ..., n is an index for experimental unit within group j,

 $j=1,\ldots,q$ is an index for levels of the between-units factor (group),

 $k=1,\ldots,p$ is an index for levels of the within-units factor (time),

 Y_{ijk} is the response measurements at time k for unit i within group j,

 μ is the overall mean,

 ${\mathcal T}_{m j}$ is the added effect for treatment group ${m j}$,

 $\delta_{i(j)}$ is the random effect due to experimental unit i within treatment group j,

 γ_k is the added effect for time k,

 $(au\gamma)_{jk}$ is the added effect for the group j imes time k interaction, and

 \mathcal{E}_{ijk} is the random error on time k for unit i within group j.

For the parameterization to be of full rank, we impose the following conditions:

$$\sum_{j=1}^{q} \tau_{j} = 0 , \quad \sum_{k=1}^{p} \gamma_{k} = 0 ,
\sum_{j=1}^{q} (\tau \gamma)_{jk} = 0 \quad \forall k = 1, ..., p , \quad \sum_{k=1}^{p} (\tau \gamma)_{jk} = 0 \quad \forall j = 1, ..., q,$$
(2)

We assume that the $\,\mathcal{E}_{ijk}$'s and the $\delta_{i(j)}$'s are independent with



Journal of Advances in Mathematics

$$\varepsilon_{ijk} \sim^{i.i.d} N(0, \sigma_{\varepsilon}^2) \text{ and } \delta_{i(j)} \sim^{i.i.d} N(0, \sigma_{\delta}^2)$$
 (3)

Let

$$X = vec(Y) = \begin{bmatrix} Y_{111} \\ \vdots \\ Y_{nqp} \end{bmatrix} = [Y_{111}, \dots, Y_{11p}, Y_{1q1}, \dots, Y_{nq1}, \dots, Y_{nqp}]'$$

Definition 1: The quadratic estimator(${\it QE}$) of σ_{δ}^2 is quadratic form which satisfies that:

$$\hat{\sigma}_{\delta}^2 = Q(A) = Y'AY.$$

For simply we denoted to $\mathit{Q}(\mathit{A})$ by A .

Let $A = \{A : A \text{ is symmetric square matrix such that } Q(A) = \hat{\sigma}_{\delta}^2 \}$

And ${\bf Q}$ is a set of any quadratic estimator (${\bf QE}\!$) of $\sigma_\delta^2.$ i.e.

$$\mathbf{Q} = \{ A = Q(A) : for any A \in A \}$$
.

Definition 2: The best quadratic unbiased estimate (BQUE) of σ_δ^2 is a quadratic estimator $\pmb{Q} \in \pmb{Q}$ satisfies that : reshape

(a)
$$E(\mathbf{Q}) = \sigma_{\delta}^{2}$$

(b) $var(\mathbf{Q}) \leq var(\mathbf{Q}^{*})$ for any $\mathbf{Q}^{*} \in \mathbf{Q}$ $\}$ (4)

Note: The general quadratic estimator for any ${m Q} \in {m Q} \;\;$ and ${m Q} \;\;$ \in A be denoted by

$$Q = X'QX = \sum_{ijk:rst} Y_{ijk} Y_{rst} q_{ijk}^{rst} \quad \text{on reshape } Q = (q_{ijk}^{rst})$$
 (5)

3. Method of Analysis of variance (ANOVA)

Sum of square to groups, subjects (group), time, group×time (interaction) and residuals are given by:

$$SS\tau = np \sum_{j=1}^{q} (\overline{y}_{j} - \overline{y}_{j})^{2} = X' \left(\frac{J_{n}}{n} \otimes I_{q} \otimes \frac{J_{p}}{p} - \frac{J_{n}}{n} \otimes \frac{J_{q}}{q} \otimes \frac{J_{p}}{p} \right) X$$
 (6)

$$SS\delta = p \sum_{i=1}^{n} \sum_{j=1}^{q} (\overline{y}_{ij.} - \overline{y}_{.j.})^2 = X' \left(I_{nq} \otimes \frac{J_p}{p} - \frac{J_n}{n} \otimes I_q \otimes \frac{J_p}{p} \right) X \tag{7}$$

$$SS\gamma = nq \sum_{j=1}^{q} (\overline{y}_{..k} - \overline{y}_{..})^2 = X' \left(\frac{J_n}{n} \otimes \frac{J_q}{q} \otimes I_p - \frac{J_n}{n} \otimes \frac{J_q}{q} \otimes \frac{J_p}{p} \right) X$$
 (8)

$$SS\tau\gamma = n\sum_{j=1}^{q} \sum_{k=1}^{p} (\overline{y}_{.jk} - \overline{y}_{.j.} - \overline{y}_{..k} + \overline{y}_{...})^{2}$$

$$= X' \left(\frac{J_{n}}{n} \otimes I_{qp} - \frac{J_{n}}{n} \otimes I_{q} \otimes \frac{J_{p}}{p} - \frac{J_{n}}{n} \otimes \frac{J_{q}}{q} \otimes I_{p} + \frac{J_{n}}{n} \otimes \frac{J_{q}}{q} \otimes \frac{J_{p}}{p} \right) X$$

$$(9)$$



$$SS\varepsilon = \sum_{i=1}^{n} \sum_{j=1}^{q} \sum_{k=1}^{p} (Y_{ijk} - \overline{y}_{.jk} - \overline{y}_{ij.} + \overline{y}_{.j.})^{2}$$

$$= X' \left(I_{nqp} - \frac{J_{n}}{n} \otimes I_{qp} - I_{nq} \otimes \frac{J_{p}}{p} + \frac{J_{n}}{n} \otimes I_{q} \otimes \frac{J_{p}}{p} \right) X$$

$$(10)$$

Where

 I_p denotes to the p imes p identity matrix, J_p denotes to p imes p matrix of 1's

and \otimes is kroncker prodect $\{IfA = (a_{ij}) \text{ and } B = (b_{rs}) \text{ then } A \otimes B = (Ab_{rs}) \}$.

And

$$\begin{split} \overline{y}_{...} &= \frac{\sum_{i=1}^n \sum_{j=1}^q \sum_{k=1}^p Y_{ijk}}{nqp} \quad \text{is the overall mean,} \\ \overline{y}_{.j.} &= \frac{\sum_{i=1}^n \sum_{k=1}^p Y_{ijk}}{np} \quad \text{is the mean for group } j, \\ \overline{y}_{ij.} &= \frac{\sum_{k=1}^p Y_{ijk}}{p} \quad \text{is the mean for the } i^{th} \text{ subject in group } j, \\ \overline{y}_{..k} &= \frac{\sum_{i=1}^n \sum_{j=1}^q Y_{ijk}}{nq} \quad \text{is the mean for time } k, \\ \overline{y}_{.jk} &= \frac{\sum_{i=1}^n Y_{ijk}}{n} \quad \text{is the mean for group } j \text{ at time } k. \end{split}$$

The above results of equation (6 -- 10) can be summarized as ANOVA Table

Table 3.1 ANOVA for one-way Repeated measures model

S.O.V.	Df	SS	MS	EMS
$ au_j$	<i>q</i> -1	SSτ	$MS\tau = \frac{SS\tau}{q-1}$	$\frac{np}{q-1} \sum_{j=1}^{q} \tau_j^2 + p\sigma_\delta^2 + \sigma_\varepsilon^2$
$\delta_{i(j)}$	q(n-1)	SSδ	$MS\delta = \frac{SS\delta}{q(n-1)}$	$p\sigma_{\delta}^2 + \sigma_{\varepsilon}^2$
γ_k	p-1	SSγ	$MS\gamma = \frac{SS\gamma}{p-1}$	$\frac{nq}{p-1}\sum_{k=1}^{p}\gamma_k^2 + \sigma_{\varepsilon}^2$



Journal of Advances in Mathematics

$(\tau\gamma)_{jk}$	(q -1)(p -1)	SSτγ	$MS\tau\gamma = \frac{SS\tau\gamma}{(q-1)(p-1)}$	$\frac{n}{(p-1)(q-1)} \sum_{j=1}^{q} \sum_{k=1}^{p} (\tau \gamma)_{jk}^{2} + \sigma_{\varepsilon}^{2}$
Eijk	q(n-1)(p-1)	SSε	$MS\varepsilon = \frac{SS\varepsilon}{q(n-1)(p-1)}$	$\sigma_{arepsilon}^2$
Total	nqp-1	SST		

The variance components can be found by solving following equations

$$MS\delta = p\sigma_{\delta}^{2} + \sigma_{\varepsilon}^{2}$$
$$MS\varepsilon = \sigma_{\varepsilon}^{2}$$

Moreover, the quadratic unbiased estimate of variance components are:

$$\hat{\sigma}_{\varepsilon}^2 = MS\varepsilon$$
 and
$$:: E(MS\delta - MS\varepsilon) = p\sigma_{\delta}^2 + \sigma_{\varepsilon}^2 - \sigma_{\varepsilon}^2 = p\sigma_{\delta}^2$$

$$:: \hat{\sigma}_{\delta}^2 = \frac{1}{n}E(MS\delta - MS\varepsilon)$$
 (11)

Now let Q(M) is quadratic form given by ANOVA method of estimating $\,\sigma_\delta^2$.

From equation (7 and 10), we can write $\boldsymbol{M} \ (= Q(M))$ as:

$$M = X'MX$$

$$= X' \left(\frac{I_{nq} \otimes \frac{J_p}{p} - \frac{J_n}{n} \otimes I_q \otimes \frac{J_p}{p}}{qp(n-1)} - \frac{I_{nqp} - \frac{J_n}{n} \otimes I_{qp} - I_{nq} \otimes \frac{J_p}{p} + \frac{J_n}{n} \otimes I_q \otimes \frac{J_p}{p}}{qp(n-1)(p-1)} \right) X$$

$$(12)$$

Then the matrix M has this form

$$M = \frac{I_{nq} \otimes \frac{J_p}{p} - \frac{J_n}{n} \otimes I_q \otimes \frac{J_p}{p}}{qp(n-1)} - \frac{I_{nqp} - \frac{J_n}{n} \otimes I_{qp} - I_{nq} \otimes \frac{J_p}{p} + \frac{J_n}{n} \otimes I_q \otimes \frac{J_p}{p}}{qp(n-1)(p-1)}$$

$$M = \frac{1}{n} \left[I_{nq} \otimes J_p - \frac{J_n}{n} \otimes I_q \otimes J_p - I_{nq} \otimes \frac{J_p}{p} + \frac{J_n}{n} \otimes I_q \otimes \frac{J_p}{p} - I_{nqp} + \frac{J_n}{n} \otimes I_{qp} \right]$$



Journal of Advances in Mathematics

$$+I_{nq}\otimes \frac{J_p}{p} - \frac{J_n}{n}\otimes I_q\otimes \frac{J_p}{p}$$

$$\Rightarrow M = \frac{1}{\eta} \left[I_{nq} \otimes J_p - \frac{J_n}{n} \otimes I_q \otimes J_p - I_{nqp} + \frac{J_n}{n} \otimes I_{qp} \right]$$

$$= \frac{1}{\eta} \left[(I_n - \frac{J_n}{n}) \otimes I_q \otimes (J_p - I_p) \right]$$
(13)

Such that $\eta = qp(n-1)(p-1)$.

If a matrix $\, \mathcal{C} \,$ have all elements of M in (13) with arrangement as.

$$C = (A+B) \otimes I_q \tag{14}$$

And
$$\mathbf{C} = Q(C) = X'CX$$
 (15)

where
$$A = \frac{(n-1)}{n\eta} (J_p \otimes I_n - I_{np})$$
 and $B = \frac{1}{n\eta} (J_p - I_p) \otimes (I_n - J_n)$

then ${\it C}$ is an another quadratic unbiased estimator of $\,\sigma_{\delta}^{2}$, ($E({\it C})=\sigma_{\delta}^{2}$).

In addition, C is a square and symmetric matrix of size $nqp \times nqp$.

The following relations can be obtained from matrix ${\cal C}$ in (14) on rewrite as ${\cal C}=\left(c_{ijk}^{rst}
ight.)$

(a)
$$\sum_{ijk} c_{ijk}^{rst} = 0$$
 for any r, s, t .
(b) $\sum_{rst} c_{ijk}^{rst} = 0$ for any i, j, k .
(c) $\sum_{jk} c_{ijk}^{rst} = 0$ for any r, s, t, i .
(d) $\sum_{st} c_{ijk}^{rst} = 0$ for any i, j, k, r .
(e) $\sum_{ijk:t} c_{ijk}^{ijt} = 1$.

Theorem1: The BQUE estimator of σ_δ^2 for model in (1) is given by ANOVA method,

that is, by quadratic form $\,\mathit{Q}(\mathit{C})\,$ state in (15).

Proof:

Let ${\pmb Q} \in {\pmb Q}$ is unbiased estimator for $\,\sigma_\delta^2$

such that $oldsymbol{Q} = oldsymbol{C} + oldsymbol{D}$

where

Volume 14 Number 01



 $\mathbf{D} = X'D X = \sum_{ijk,rst} Y_{ijk} Y_{rst} d_{ijk}^{rst} \quad and \quad q_{ijk}^{rst} = c_{ijk}^{rst} + d_{ijk}^{rst}$ (17)

$$Q = (q_{ijk}^{rst}), D = (d_{ijk}^{rst})$$
 and $C = (c_{ijk}^{rst})$

In problem (17), by give requirement to each q_{ijk}^{rst} (since $m{Q}$ satisfies (4) and c_{ijk}^{rst} are known) then the problem(17) reduces to giving exact values to each d_{ijk}^{rst} .

When
$$m{Q} = m{C} + m{D}
ightarrow E(m{Q}) = E(m{C} + m{D}) = \sigma_\delta^2$$
 since $E(m{Q}) = \sigma_\delta^2$

this reduces to

$$\sum_{R} \left(\mu + \tau_{j} + \gamma_{k} + (\tau \gamma)_{jk} \right) \left(\mu + \tau_{s} + \gamma_{t} + (\tau \gamma)_{st} \right) \left(c_{ijk}^{rst} + d_{ijk}^{rst} \right)$$

$$+ \sum_{R(r=i,s=j)} \sigma_{\delta}^{2} \left(c_{ijk}^{rst} + d_{ijk}^{rst} \right) + \sum_{ijk} \sigma_{\varepsilon}^{2} \left(c_{ijk}^{ijk} + d_{ijk}^{ijk} \right) = \sigma_{\delta}^{2}$$

$$(18)$$

where index R is refers to all indexes: $1 \le (i, r) \le n$, $1 \le (j, s) \le q$, $1 \le (k, t) \le p$.

And index R(l) is refers to all indexes: $1 \le (i, r) \le n, 1 \le (j, s) \le q, 1 \le (k, t) \le p$.

Such that the restriction condition l is satisfied.

From above equation (18) and by using (16 and 2) we have

$$\sum_{R} d_{ijk}^{rst} = 0 \qquad \equiv \sum_{ijk;rst} d_{ijk}^{rst} = 0
\sum_{R(r=i;s=j)} d_{ijk}^{rst} = 0 \qquad \equiv \sum_{ijk;t} d_{ijk}^{ijt} = 0
\sum_{R(r=i;s=j;t=k)} d_{ijk}^{rst} = 0 \equiv \sum_{ijk} d_{ijk}^{ijk} = 0$$
(19)

Now since $E(\boldsymbol{Q}) = \sigma_{\delta}^2$ then

$$var(\mathbf{Q}) = E(\mathbf{Q}^2) - \sigma_{\delta}^4 = E(\mathbf{C}^2) + E(\mathbf{D}^2) + 2E(\mathbf{C}\mathbf{D}) - \sigma_{\delta}^4$$
 (20)

We will study the term (CD).

$$E(\mathbf{CD}) = E(\sum_{R} Y_{ijk} Y_{rst} c_{ijk}^{rst} \sum_{P} Y_{fah} Y_{uvw} d_{fah}^{uvw})$$

where index P defined as R but for subscripts f, g, h, u, v, w it is refers to all indexes: $1 \le (f, u) \le n$, $1 \le (g, v) \le q$, $1 \le (h, w) \le p$.

From (15) and (1)

$$\because \mathbf{C} = \sum_{R} Y_{ijk} Y_{rst} c_{ijk}^{rst} \text{ and } Y_{ijk} = \mu + \tau_j + \delta_{i(j)} + \gamma_k + (\tau \gamma)_{jk} + \varepsilon_{ijk}$$



we have

$$\mathbf{C} = \sum_{R} \left[\mu + \tau_{j} + \delta_{i(j)} + \gamma_{k} + (\tau \gamma)_{jk} + \varepsilon_{ijk} \right] \left[\mu + \tau_{s} + \delta_{r(s)} + \gamma_{t} + (\tau \gamma)_{st} + \varepsilon_{rst} \right] c_{ijk}^{rst}$$

$${\cal C} = \sum_R \! \left[\delta_{i(j)} + \varepsilon_{ijk} \right] \! \left[\delta_{r(s)} + \, \varepsilon_{rst} \right] \! c_{ijk}^{rst}$$
 , we using (16: c and d)

$$E(\mathbf{C}) = E\left(\sum_{R} \left[\delta_{i(j)} + \varepsilon_{ijk}\right] \left[\delta_{r(s)} + \varepsilon_{rst}\right] c_{ijk}^{rst}\right)$$
(21)

$$\dot{\varepsilon} E(\mathbf{CD}) = E\left(\sum_{R} \left[\delta_{i(j)} + \varepsilon_{ijk}\right] \left[\delta_{r(s)} + \varepsilon_{rst}\right] c_{ijk}^{rst} \sum_{P} \left[\mu + \tau_g + \delta_{f(g)} + \gamma_h + (\tau \gamma)_{gh} + \varepsilon_{fgh}\right] \left[\mu + \tau_v + \delta_{u(v)} + \gamma_w + (\tau \gamma)_{vw} + \varepsilon_{uvw}\right] d_{fgh}^{uvw}\right)$$

$$= E\left(\sum_{R}\sum_{p} \left[\delta_{i(j)} + \varepsilon_{ijk}\right] \left[\delta_{r(s)} + \varepsilon_{rst}\right] \left[\mu + \tau_{g} + \delta_{f(g)} + \gamma_{h} + (\tau\gamma)_{gh} + \varepsilon_{fgh}\right] \left[\mu + \tau_{v} + \delta_{u(v)} + \gamma_{w} + (\tau\gamma)_{vw} + \varepsilon_{uvw}\right] c_{ijk}^{rst} d_{fgh}^{uvw}$$

$$+ \varepsilon_{uvw} c_{ijk}^{rst} d_{fgh}^{uvw}$$

$$+ (22)$$

From equations in [(2), (16) and (19)], since \mathcal{E}_{ijk} 's and the $\delta_{i(j)}$'s are independent with

 $\varepsilon_{ijk} \sim^{i.i.d} N\left(0, \sigma_{\varepsilon}^2\right)$ and $\delta_{i(j)} \sim^{i.i.d} N\left(0, \sigma_{\delta}^2\right)$ we have all terms of multiply the element of (22) equal to zero.

That is mean the equation in (20) becomes

when
$$E(\mathbf{CD}) = 0$$
 then we have

$$var(\mathbf{Q}) = E(\mathbf{Q}^2) - \sigma_{\delta}^4 = E(\mathbf{C}^2) + E(\mathbf{D}^2) - \sigma_{\delta}^4$$
$$= var(\mathbf{C}) + E\left(\sum_{ijk=1}^{n} [Y_{ijk}Y_{rst}d_{ijk}^{rst}]^2\right)$$

Then $m{Q}$ has minimum variance if $d_{ijk}^{rst}=0$ for all i,j,k;r,s,t. This clear implies to $m{Q}=m{C}.$

By above proof, we shown that, the **BQUE** of σ_δ^2 is $\hat{\sigma}_\delta^2 = \mathbf{C} = Y'CY$, where C is given in equation (14) on rewrite as $C = (c_{ijk}^{rst})$.

And same manner we can found the **BQUE** for $\,\sigma_{arepsilon}^{\,2}$, which equal to

$$(\hat{\sigma}_{\varepsilon}^2 = \mathbf{E} = Y'EY)$$



Journal of Advances in Mathematics

where
$$E=\left(e_{ijk}^{rst}\right)$$
, i.e E is reshape of $\left(I_{np}-\frac{J_n}{n}\otimes I_p-I_n\otimes \frac{J_p}{p}+\frac{J_{np}}{np}\right)\otimes I_q$.

REFERENCES

- [1] AL-Mouel, A. H. S., A.J. Mohaisen and Khawla (2017). Bayesian One- Way Repeated Measurements Model Based on Bayes Quadratic Unbiased Estimator, Journal of Advance in Mathematics, Vol. 13, No. 2, pp. 7176-7182.
- [2] AL-Mouel, A. H. S. and Wang, J. L. (2004). One-Way Multivariate Repeated Measurements Analysis of Variance Model. Applied Mathematics a Journal of Chinese Universities, 19, 4, 435-448.
- [3] AL-Mouel, A. H. S. (2004). Nested repeated measures model sufficiency and estimation. Chinese Journal of Applied Probability and Statistics, 20, 133-146.
- [4] Crump S. L. (1946), The estimation of variance components in the analysis of variance, Biometrics Bulletin, Vol. 2, pp. 7-11.
- [5] Graybill F.A. (1954), On quadratic estimates of variance components, Journal paper No. J-2-171 of the lowa Agricultural Experiment Station, Ames, Iowa, pp. 367-372.
- [6] James R. S. (2017), Matrix Analysis for Statistics , Third Edition, John Wiley & Sons, Inc., Canada.
- [7] Rao, C. R. (1971b), Minimum variance quadratic unbiased estimation of variance components. J. Multivariate Anal., 1(4), 445–456.
- [8] Sahai, H. and Ojeda, M. M. (2005), Analysis of variance for random models, Birkhäuser Boston, USA.
- [9] Vonesh, E.F. and Chinchilli, V. M. (1997) linear and nonlinear models for the analysis of Repeated Measurements, Marcel Dakker, Inc. New York.