# Continuous Generalized Hankel-type integral wavelet transformation 

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#### Abstract

Using the theory of Hankel-type convolution, continuous generalized Hankel-type wavelet integral transformation is defined. The generalized Hankel-type integral wavelet transformation is developed. Using the developed theory of generalized Hankel-type convolution, the generalized Hankel-type translation is introduced. Properties of the kernel $D_{\mu, \alpha, \beta, v}(x, y, z)$ are developed in the study. Using the properties of kernel, the generalized Hankel-type wavelet transformation is defined. The existence of the generalized Hankel-type integral wavelet transformation is given by a theorem. The boundedness and inversion formula for the generalized Hankel-type integral wavelet transformation is obtained. A basic wavelet which defines continuous generalized Hankel-type integral wavelet transformation, its admissibility conditions and the wavelet to the function is proved. Examples have been shown to explain the studied continuous generalized Hankel-type integral wavelet transformation.


## INDEXING TERMS/KEYWORDS

Continuous generalized Hankel-type integral wavelet transformation; generalized Hankel-type transformation; Hankel-type Convolution.

## SUBJECT CLASSIFICATION

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## 1. INTRODUCTION

Malgonde [1] investigated the following generalized Hankel-type integral transformation
$F_{1}(t)=\left(F_{1, \mu, \alpha, \beta, v} f\right)(t)=v \beta t^{-1-2 \alpha+2 v} \int_{0}^{\infty}(x t)^{\alpha} J_{\mu}\left[\beta(x t)^{v}\right] f(x) d x$,
$J_{\mu}(x)$ being the Bessel function of the first kind of order $\mu \geq-1 / 2$.
We define $L_{p}(0, \infty), 1 \leq p \leq \infty$, as the space of real measurable function $\phi$ on $(0, \infty)$ for which
$\|\phi\|_{\mu, v, p}=\left(\int_{0}^{\infty}\left|x^{\mu \nu-\alpha} \phi(x)\right|^{p} \frac{d x}{x}\right)^{1 / p}, 1 \leq p<\infty$
$\|\phi\|_{\infty}=\underset{0<x<\infty}{\operatorname{ess} \sup }\left|x^{\mu \nu-\alpha} \phi(x)\right|<\infty$.
For each $\phi \in L_{1}(0, \infty)$, generalized Hankel-type integral transformation of $\phi$ is defined by
$\hat{\phi}(x)=v \beta t^{-1-2 \alpha+2 v} \int_{0}^{\infty}(x t)^{\alpha} J_{\mu}\left[\beta(x t)^{v}\right] \phi(t) d t, 0<t<\infty$.
From [1] we know that $\hat{\phi}(x)$ is bounded and continuous on $(0, \infty)$ and $\|\hat{\phi}(x)\|_{\infty} \leq\|\phi\|_{1}$.
If $f(x)$ is of bounded variation into a neighborhood of the point $x=x_{0}>0, \mu \geq-1 / 2$ and the integral $\int_{0}^{\infty}|f(x)| x^{\alpha-v / 2}$ exists, then the inversion formula in [2] is given by
$\lim _{R \rightarrow \infty} v \beta y_{0}^{-1-2 \alpha+2 v} \int_{0}^{R}\left(x_{0} y\right)^{\alpha} J_{\mu}\left[\beta\left(x_{0} y\right)^{\nu}\right] F_{1}(y) d y=\frac{1}{2}\left[f\left(x_{0}+0\right)+f\left(x_{0}-0\right)\right]$.
If $f(x) x^{-\alpha-\mu}$ and $F_{2}(y) y^{\mu-\alpha-1+2 v}$ are in $L_{1}(0, \infty)$, for
$F_{1}(t)=\left(F_{1, \mu, \alpha, \beta, v} f(x)\right)(t)=v \beta t^{-1-2 \alpha+2 v} \int_{0}^{\infty}(x t)^{\alpha} J_{\mu}\left[\beta(x t)^{v}\right] f(x) d x$,
and

$$
F_{2}(t)=\left(F_{2, \mu, \alpha, \beta, v} g(x)\right)(t)=v \beta t^{-1-2 \alpha+2 v} \int_{0}^{\infty}(x t)^{\alpha} J_{\mu}\left[\beta(x t)^{v}\right] \mathrm{g}(x) d x, \text { for } \mu \geq-1 / 2
$$

the following mixed Parseval formula holds for $F_{1}$-transformation by [2];
$\int_{0}^{\infty} f(x) g(x) d x=\int_{0}^{\infty} F_{1}(y) F_{2}(y) d y$.
To define the generalized Hankel-type Convolution, we need to introduce generalized Hankel-type translation. Define
$D_{\mu, \alpha, \beta, v}(x, y, z)$
$=\int_{0}^{\infty} t^{-\mu \nu-\alpha} v \beta t^{-1-2 \alpha+2 v}(x t)^{\alpha} J_{\mu}\left[\beta(x t)^{\nu}\right] v \beta t^{-1-2 \alpha+2 v}(y t)^{\alpha} J_{\mu}\left[\beta(y t)^{\nu}\right] v \beta t^{-1-2 \alpha+2 v}(z t)^{\alpha} J_{\mu}\left[\beta(z t)^{\nu}\right] d t$.

Properties of the kernel $D_{\mu, \alpha, \beta, \nu}(x, y, z)$ :
Following [3] properties are established:
i) For $0<x, y<\infty$ and $0 \leq t<\infty$, we have
$\int_{0}^{\infty} \nu \beta t^{\mu \nu+\alpha} z^{-1-2 \alpha+2 v}(z t)^{\alpha} J_{\mu}\left[\beta(z t)^{\nu}\right] D_{\mu, \alpha, \beta, \nu}(x, y, z) d z=(\nu \beta)^{2}(x y)^{-1-2 \alpha+2 \nu}(x t)^{\alpha} J_{\mu}\left[\beta(x t)^{\nu}\right](y t)^{\alpha} J_{\mu}\left[\beta(y t)^{\nu}\right]$
Proof:

$$
\begin{aligned}
& D_{\mu, \alpha, \beta, \nu}(x, y, z)=(v \beta)^{3} \int_{0}^{\infty} t^{-\mu \nu-\alpha} z^{-1-2 \alpha+2 v}(z t)^{\alpha} J_{\mu}\left[\beta(z t)^{\nu}\right]\left[x^{-1-2 \alpha+2 v}(x t)^{\alpha} J_{\mu}\left[\beta(x t)^{\nu}\right] y^{-1-2 \alpha+2 v}(y t)^{\alpha} J_{\mu}\left[\beta(y t)^{\nu}\right]\right] d z \\
&=\int_{0}^{\infty} \nu \beta t^{-\mu \nu-\alpha} z^{-1-2 \alpha+2 v}\left[(v \beta)^{2}(x y)^{-1-2 \alpha+2 v}(x t)^{\alpha} J_{\mu}\left[\beta(x t)^{\nu}\right](y t)^{\alpha} J_{\mu}\left[\beta(y t)^{\nu}\right]\right](z t)^{\alpha} J_{\mu}\left[\beta(z t)^{\nu}\right] d z \\
&=t^{-\mu \nu-\alpha} F_{1, \mu, \alpha, \beta, \nu}\left\{(\nu \beta)^{2}(x y)^{-1-2 \alpha+2 v}(x t)^{\alpha} J_{\mu}\left[\beta(x t)^{\nu}\right](y t)^{\alpha} J_{\mu}\left[\beta(y t)^{\nu}\right]\right\} \\
& F_{1, \mu, \alpha, \beta, \nu}^{-1}\left\{t^{\mu \nu+\alpha} D_{\mu, \alpha, \beta, \nu}(x, y, z)\right\}=(v \beta)^{2}(x y)^{-1-2 \alpha+2 v}(x t)^{\alpha} J_{\mu}\left[\beta(x t)^{\nu}\right](y t)^{\alpha} J_{\mu}\left[\beta(y t)^{\nu}\right]
\end{aligned}
$$

Applying the inversion formula of generalized Hankel-type integral transformation to (1.2)
$\int_{0}^{\infty} v \beta t^{\mu v+\alpha} z^{-1-2 \alpha+2 v}(z t)^{\alpha} J_{\mu}\left[\beta(z t)^{\nu}\right] D_{\mu, \alpha, \beta, v}(x, y, z) d z$
$=(\nu \beta)^{2}(x y)^{-1-2 \alpha+2 v}(x t)^{\alpha} J_{\mu}\left[\beta(x t)^{\nu}\right](y t)^{\alpha} J_{\mu}\left[\beta(y t)^{\nu}\right]$.
and hence the result. In particular, taking $t=0$, gives
ii) $\int_{0}^{\infty} v \beta t^{\mu \nu+\alpha} z^{-1-2 \alpha+2 v}(z t)^{\alpha} J_{\mu}\left[\beta(z t)^{\nu}\right] D_{\mu, \alpha, \beta, \nu}(x, y, z) d z=1$,
i.e. for which $x, y>0, D_{\mu, \alpha, \beta, v}(x, y, z)$ belongs to $L_{0, \alpha, \beta, v, \mu}^{1}(0, \infty)$.
iii) $0<x, y, z<\infty, D_{\mu, \alpha, \beta, v}(x, y, z) \geq 0$.
iv) $D_{\mu, \alpha, \beta, \nu}(x, y, z)=D_{\mu, \alpha, \beta, \nu}(y, x, z)=D_{\mu, \alpha, \beta, \nu}(z, x, y)=\ldots$

The generalized Hankel-type integral translation $T_{y}$ of $\phi \in L_{p}(0, \infty), 1 \leq p \leq \infty$, is defined by
$T_{y} \phi(x)=\phi(x, y)=\int_{0}^{\infty} \phi(z) D_{\mu, \alpha, \beta, v}(x, y, z) d z, 0<x, y<\infty$.
The map $y \rightarrow T_{y} \phi$ is continuous from $(0, \infty)$ into $(0, \infty)$.
Let $p, q, r \in[1, \infty)$ and $\frac{1}{r}=\frac{1}{p}+\frac{1}{q}-1$. The generalized Hankel-type integral convolution of
$\phi \in L_{p}(0, \infty)$ and $\psi \in L_{p}(0, \infty)$ is defined by $(\phi \# \psi)(x)=\int_{0}^{\infty} \phi(x, y) \psi(y) d y$.
In [4] the integral is convergent for almost all $x, 0<x<\infty$ and $\|\phi \# \psi\|_{r} \leq\|\phi\|_{p}\|\psi\|_{q}$.

Moreover, $p=\infty$, then $(\phi \# \psi)(x)$ is defined for all $x, 0<x<\infty$ and is continuous.
If $\phi, \psi \in L_{1}(0, \infty)$, then $(\phi \# \psi) \wedge(t)=\hat{\phi}(t) \hat{\psi}(t), 0 \leq t<\infty$.
In this paper, in terms of the aforesaid generalized Hankel-type translation $T_{y}$ and dilation $D_{a}$ defined by

$$
\begin{equation*}
D_{\mu, \alpha, \beta, v, a} \phi(x, y)=a^{-2(\mu v-\alpha)-3 v} \phi(x / a, y / a) \tag{1.3}
\end{equation*}
$$

is a continuous generalized Hankel-type integral wavelet transformation is defined. Its continuity and boundedness properties are established. An inversion formula is obtained.

## 2. CONTINUOUS GENERALIZED HANKEL-TYPE INTEGRAL WAVELET TRANSFORMATION

Let $\psi \in L_{p}(0, \infty), 1 \leq p<\infty$ be given. For $b \geq 0$ and $a>0$ define the generalized Hankel-type integral wavelet transformation
$\psi_{b, a}(x)=D_{\mu, \alpha, \beta, v, a} T_{y} \psi(x)=D_{\mu, \alpha, \beta, v, a} \psi(b, x)=a^{-2(\mu \nu-\alpha)-3 v} \psi(b / a, x / a)$

$$
=a^{-2(\mu v-\alpha)-3 v} \int_{0}^{\infty} D_{\mu, \alpha, \beta, v}(b / a, x / a, z) \psi(z) d z,
$$

the integral being convergent by virtue of [8].
Using the wavelet $\psi_{b, a}$, define the generalized Hankel-type integral wavelet transformation,

$$
\begin{aligned}
H_{1, \alpha, \beta, v, \mu}(b, a) & =\left(H_{1, \alpha, \beta, \nu, \mu, \psi} f\right)(b, a) \\
& =\left\langle f(t), \psi_{b, a}(t)\right\rangle \\
& =\int_{0}^{\infty} f(t) \overline{\psi_{b, a}(t)} d t \\
& =a^{-2(\mu v-\alpha)-3 \nu} \int_{0}^{\infty} \int_{0}^{\infty} f(t) \overline{\psi(z)} D_{\mu, \alpha, \beta, v}(b / a, t / a, z) d z d t
\end{aligned}
$$

provided the integral is convergent.
The continuity of the generalized Hankel-type integral wavelet follows from the boundedness property of the generalized Hankel-type translation [5].

Lemma 1: Let $\psi \in L_{p}(0, \infty), 1 \leq p<\infty$. Then for $y \geq 0$, the map $y \rightarrow T_{y} f$ is continuous from $L_{p}(0, \infty)$ into $L_{p}(0, \infty)$. The function $\psi_{b, a}$ is defined almost everywhere on $[0, \infty)$, and $\left\|\psi_{b, a}(x)\right\|_{p} \leq a^{(2(\mu v-\alpha)+3 v)(1 / p-1)}\|\psi\|_{p}$.

The existence of the generalized Hankel-type transformation is given by the following theorem.
Theorem 2. Let $f \in L_{p}(0, \infty)$ and $\psi \in L_{p}(0, \infty)$ with $1 \leq p, q<\infty$ and
$\frac{1}{p}+\frac{1}{q}=1 ; H_{1, \alpha, \beta, \nu, \mu}(b, a)=\left(H_{1, \alpha, \beta, v, \mu, \mu} f\right)(b, a)$ be the continuous wavelet transform. Then

1) $\left(H_{1, \alpha, \beta, v, \mu} f\right)(b, a)$ is continuous on $(0, \infty) \times(0, \infty)$,
2) $\left\|\left(\left(H_{1, \alpha, \beta, \nu, \mu, \psi} f\right)(b, a) f\right)(b, a)\right\|_{r} \leq a^{2(\mu v-\alpha)+3 v}\|f\|_{p}\|\psi\|_{q}, \frac{1}{r}=\frac{1}{p}+\frac{1}{q}-1,1 \leq p, q, r<\infty$,
3) $\left\|\left(\left(H_{1, \alpha, \beta, v, \mu, \psi} f\right)(b, a) f\right)(b, a)\right\|_{\infty} \leq a^{(2(\mu v-\alpha)+3 v)\left(\frac{1}{q}-1\right)}\|f\|_{p}\|\psi\|_{q}, \frac{1}{p}+\frac{1}{q}=1$.

## Proof.

1) Let $\left(b_{0}, a_{0}\right)$ be an arbitrary but fixed point in $(0, \infty) \times(0, \infty)$. Then by Hölder's inequality,

$$
\begin{aligned}
& \left|\left(H_{1, \alpha, \beta, v, \mu} f\right)(b, a)-\left(H_{1, \alpha, \beta, v, \mu} f\right)\left(b_{0}, a_{0}\right)\right| \\
& \leq a^{-2(\mu \nu-\alpha)-3 v} \int_{0}^{\infty} \int_{0}^{\infty} \mid f(t) \psi(z)\left[D_{\mu, \alpha, \beta, v}(b / a, t / a, z)-D_{\mu, \alpha, \beta, v}\left(b_{0} / a_{0}, t / a_{0}, z\right)\right] d t d z \\
& \leq a^{-2(\mu v-\alpha)-3 v}\left[\int_{0}^{\infty} \int_{0}^{\infty}|f(t)|^{p}\left|D_{\mu, \alpha, \beta, v}(b / a, t / a, z)-D_{\mu, \alpha, \beta, v}\left(b_{0} / a_{0}, t / a_{0}, z\right)\right| d t d z\right]^{1 / p} \\
& \quad \times\left[\int_{0}^{\infty} \int_{0}^{\infty}|\psi(z)|^{q}\left|D_{\mu, \alpha, \beta, v}(b / a, t / a, z)-D_{\mu, \alpha, \beta, v}\left(b_{0} / a_{0}, t / a_{0}, z\right)\right| d t d z\right]^{1 / q}
\end{aligned}
$$

Since by (9) $\int_{0}^{\infty}\left|D_{\mu, \alpha, \beta, \nu}(b / a, t / a, z)-D_{\mu, \alpha, \beta, \nu}\left(b_{0} / a_{0}, t / a_{0}, z\right)\right| d t \leq 2$, by dominated convergence theorem and continuity of $D_{\mu, \alpha, \beta, v}(b / a, t / a, z)$ in the variables $b$ and $a$, we have $\lim _{\substack{b \rightarrow b_{0} \\ a \rightarrow a_{0}}}\left|\left(H_{1, \alpha, \beta, v, \mu} f\right)(b, a)-\left(H_{1, \alpha, \beta, v, \mu} f\right)\left(b_{0}, a_{0}\right)\right|=0$. This proves that $H(b, a)$ is continuous on $(0, \infty) \times(0, \infty)$.
2) $\quad\left\|\left(\left(H_{1, \alpha, \beta, v, \mu, \psi} f\right)(b, a) f\right)(b, a)\right\|_{r} \leq a^{2(\mu \nu-\alpha)+3 v}\|f\|_{p}\|\psi\|_{q}, \frac{1}{r}=\frac{1}{p}+\frac{1}{q}-1,1 \leq p, q, r<\infty$.
3) It can be proved using Hölder's inequality.

## 3. AN INVERSION FORMULA

In this section, we show that the function $f$ can be recovered from its wavelet transform when the wavelet $\psi$ satisfies admissibility condition.
Theorem 3. Let $\psi \in L^{2}\left(\mathrm{R}_{+}\right)$be a basic wavelet which defines generalized Hankel-type wavelet integral transformation. Then, for $A_{\psi}=\int_{0}^{\infty} w^{-2(\mu v-\alpha)-3 v}|\hat{\psi}(w)|^{2} d w>0$, we have

$$
\begin{array}{r}
\int_{0}^{\infty} \int_{0}^{\infty}\left(\left(H_{1, \alpha, \beta, v, \mu, \psi} f\right)(b, a) f\right)(b, a) \overline{\left(\left(H_{1, \alpha, \beta, v, \mu, \psi} f\right)(b, a) g\right)(b, a)} a^{-2(\mu v-\alpha)-3 v} d a d b \\
=A_{\psi}\langle f, g\rangle \text { for all } f, g \in L^{2}\left(\mathrm{R}_{+}\right) .
\end{array}
$$

Proof. The representation for $\left(H_{1, \alpha, \beta, v, \mu, \psi} f\right)(b, a)$, can be expressed as
$\left(H_{1, \alpha, \beta, \nu, \mu, \psi} f\right)(b, a)$
$=\int_{0}^{\infty} \int_{0}^{\infty} f(t) \overline{\psi(z)} D_{\mu, \alpha, \beta, v}(b / a, t / a, z) d z d t$
$=a^{-2(\mu v-\alpha)-3 v} \int_{0}^{\infty} \int_{0}^{\infty} \hat{f}(x / a) \overline{\psi(z)}\left[\begin{array}{l}\left\{v \beta\left(\frac{b}{a}\right)^{-1-2 \alpha+2 v}\left(\frac{x b}{a}\right)^{\alpha} J_{\mu}\left[\beta\left(\frac{x b}{a}\right)^{v}\right]\right\} \\ \left\{v \beta z^{-1-2 \alpha+2 v}(z a x)^{\alpha} J_{\mu}\left[\beta(z a x)^{v}\right]\right\}\end{array}\right] d x d z$
$=a^{-2(\mu \nu-\alpha)-3 \nu} \int_{0}^{\infty} \hat{f}(x / a) \overline{\hat{\psi}(x)}\left\{v \beta\left(\frac{b}{a}\right)^{-1-2 \alpha+2 v}\left(\frac{x b}{a}\right)^{\alpha} J_{\mu}\left[\beta\left(\frac{x b}{a}\right)^{\nu}\right]\right\} d x$
$=\int_{0}^{\infty} \hat{f}(u) \overline{\hat{\psi}(a u)}\left\{v \beta b^{-1-2 \alpha+2 v}(b u)^{\alpha} J_{\mu}\left[\beta(b u)^{v}\right]\right\} d u$
$=(\hat{f}(u) \overline{\hat{\psi}(a u)}) \wedge(b)$.
Parseval identity yields

$$
\begin{aligned}
& \int_{0}^{\infty}\left(H_{1, \alpha, \beta, v, \mu, \psi} f\right)(b, a) \overline{\left(H_{1, \alpha, \beta, v, \mu, \psi} f\right)(b, a)} d b \\
& \quad=\int_{0}^{\infty}(\hat{f}(u) \overline{\hat{\psi}(a u)}) \wedge(b) \overline{(\hat{g}(u) \overline{\hat{\psi}(a u)})} \wedge(b) d b \\
& \quad=\int_{0}^{\infty}(\hat{f}(u) \overline{\hat{\psi}(a u)}) \overline{(\hat{g}(u) \overline{\hat{\psi}(a u)})} d u .
\end{aligned}
$$

Now multiplying by $a^{-2(\mu v-\alpha)-3 v} d a$ and integrating, we get

$$
\begin{aligned}
& \int_{0}^{\infty} \int_{0}^{\infty}\left(H_{1, \alpha, \beta, v, \mu, \psi} f\right)(b, a) \overline{\left(H_{1, \alpha, \beta, v, \mu, \psi} f\right)(b, a)} d b a^{-2(\mu v-\alpha)-3 v} d a \\
&=\int_{0}^{\infty} \int_{0}^{\infty}\left(\hat{f}(u) \overline{\hat{\psi}(a u)} \overline{(\hat{g}(u) \overline{\hat{\psi}(a u)})} d u \cdot a^{-2(\mu v-\alpha)-3 v} d a\right. \\
&=\int_{0}^{\infty} \hat{f}(u) \overline{\hat{g}(u)} d u \int_{0}^{\infty} \hat{\psi}(a u) \overline{\hat{\psi}(a u)} \cdot a^{-2(\mu v-\alpha)-3 v} d a \\
&=\int_{0}^{\infty} \hat{f}(u) \overline{\hat{g}(u)} d u \int_{0}^{\infty}|\hat{\psi}(a u)|^{2} \cdot a^{-2(\mu v-\alpha)-3 v} d a \\
&=\int_{0}^{\infty} \hat{f}(u) \overline{\hat{g}(u)} d u \int_{0}^{\infty}|\hat{\psi}(w)|^{2} \cdot w^{-2(\mu v-\alpha)-3 v} d w \\
&=A_{\psi}\langle f, g\rangle .
\end{aligned}
$$

Notice that admissibility condition requires that $\hat{\psi}(0)=0$. If $\hat{\psi}$ is continuous, it follows that $\int_{0}^{\infty} \psi(x) d x=0$. This justifies the wavelet to the function.

Now consider
$\psi\left(\frac{b}{a}, \frac{t}{a}\right)=\psi(x, y)$ by putting $\frac{b}{a}=x$ and $\frac{t}{a}=y$. Then $\psi(x, y)=\int_{0}^{\infty} \psi(z) D_{\mu, \alpha, \beta, \nu}(b / a, t / a, z) d z$.
Since
$D_{\mu, \alpha, \beta, v}(x, y, z)=\int_{0}^{\infty} \xi^{-\mu \nu-\alpha}\left[\begin{array}{l}v \beta x^{-1-2 \alpha+2 v}(x \xi)^{\alpha} J_{\mu}\left[\beta(x \xi)^{\nu}\right] \\ \left.v \beta y^{-1-2 \alpha+2 v}(y \xi)^{\alpha} J_{\mu}\left[\beta(y \xi)^{\nu}\right] v \beta z^{-1-2 \alpha+2 v}(z \xi)^{\alpha} J_{\mu}\left[\beta(z \xi)^{\nu}\right] d \xi\right] . . ~ . ~ . ~\end{array}\right.$
Substituting the expression becomes

$$
\begin{aligned}
\psi(x, y) & =\int_{0}^{\infty} \psi(z)\left[\int_{0}^{\infty} \xi^{-\mu v-\alpha}\left\{\begin{array}{l}
v \beta x^{-1-2 \alpha+2 v}(x \xi)^{\alpha} J_{\mu}\left[\beta(x \xi)^{\nu}\right] \\
v \beta y^{-1-2 \alpha+2 v}(y \xi)^{\alpha} J_{\mu}\left[\beta(y \xi)^{\nu}\right] \\
\left.v \beta z^{-1-2 \alpha+2 v}(z \xi)^{\alpha} J_{\mu}\left[\beta(z \xi)^{\nu}\right] d \xi\right]
\end{array}\right\} d z\right. \\
& =\int_{0}^{\infty}\left(\int_{0}^{\infty} \psi(z) \nu \beta z^{-1-2 \alpha+2 v}(z \xi)^{\alpha} J_{\mu}\left[\beta(z \xi)^{\nu}\right] d z\right) \xi^{-\mu v-\alpha}\left\{\begin{array}{l}
v \beta x^{-1-2 \alpha+2 v}(x \xi)^{\alpha} J_{\mu}\left[\beta(x \xi)^{\nu}\right] \\
v \beta y^{-1-2 \alpha+2 v}(y \xi)^{\alpha} J_{\mu}\left[\beta(y \xi)^{\nu}\right]
\end{array}\right\} d \xi \\
& =\int_{0}^{\infty} \xi^{-\mu \nu-\alpha}\left\{\nu \beta x^{-1-2 \alpha+2 v}(x \xi)^{\alpha} J_{\mu}\left[\beta(x \xi)^{\nu}\right] v \beta y^{-1-2 \alpha+2 v}(y \xi)^{\alpha} J_{\mu}\left[\beta(y \xi)^{\nu}\right]\right\}\left(F_{1, \mu, \alpha, \beta, \nu} \psi\right)(\xi) d \xi .
\end{aligned}
$$

Substitute $\frac{b}{a}=x$ and $\frac{t}{a}=y$.

$$
\begin{aligned}
& \psi\left(\frac{b}{a}, \frac{t}{a}\right)=\int_{0}^{\infty} \xi^{-\mu \nu-\alpha}\left\{\nu \beta\left(\frac{b}{a}\right)^{-1-2 \alpha+2 v}\left(\frac{b \xi}{a}\right)^{\alpha} J_{\mu}\left[\beta\left(\frac{b \xi}{a}\right)^{\nu}\right] \nu \beta\left(\frac{t}{a}\right)^{-1-2 \alpha+2 v}\left(\frac{t \xi}{a}\right)^{\alpha} J_{\mu}\left[\beta\left(\frac{t \xi}{a}\right)^{\nu}\right]\right\}\left(F_{1, \mu, \alpha, \beta, \nu} \psi\right)(\xi) d \xi . \\
& \left(H_{1, \alpha, \beta, \nu, \mu, \psi} f\right)(b, a) \\
& =a^{-2(\mu v-\alpha)-3 v} \int_{0}^{\infty} \psi\left(\frac{b}{a}, \frac{t}{a}\right) f(t) d t \\
& =a^{-2(\mu \nu-\alpha)-3 \nu} \int_{0}^{\infty}\left(\int_{0}^{\infty} \xi^{-\mu \nu-\alpha}\left\{\begin{array}{l}
v \beta\left(\frac{b}{a}\right)^{-1-2 \alpha+2 v}\left(\frac{b \xi}{a}\right)^{\alpha} J_{\mu}\left[\beta\left(\frac{b \xi}{a}\right)^{\nu}\right] \\
v \beta\left(\frac{t}{a}\right)^{-1-2 \alpha+2 v}\left(\frac{t \xi}{a}\right)^{\alpha} J_{\mu}\left[\beta\left(\frac{t \xi}{a}\right)^{\nu}\right]
\end{array}\right\}\left(F_{1, \mu, \alpha, \beta, \nu} \psi\right)(\xi) d \xi\right] \times f(t) d t . \\
& =a^{-2(\mu v-\alpha)-3 v} \int_{0}^{\infty} \nu \beta\left(\frac{b}{a}\right)^{-1-2 \alpha+2 v}\left(\frac{b \xi}{a}\right)^{\alpha} J_{\mu}\left[\beta\left(\frac{b \xi}{a}\right)^{\nu}\right]\left(\int_{0}^{\infty} \nu \beta\left(\frac{t}{a}\right)^{-1-2 \alpha+2 v}\left(\frac{t \xi}{a}\right)^{\alpha} J_{\mu}\left[\beta\left(\frac{t \xi}{a}\right)^{\nu}\right] f(t) d t\right) \\
& \times \xi^{-\mu \nu-\alpha}\left(F_{1, \mu, \alpha, \beta, \psi} \psi\right)(\xi) d \xi \\
& =a^{-2(\mu \nu-\alpha)-3 v} \int_{0}^{\infty} \nu \beta\left(\frac{b}{a}\right)^{-1-2 \alpha \alpha 2 v}\left(\frac{b \xi}{a}\right)^{\alpha} J_{\mu}\left[\beta\left(\frac{b \xi}{a}\right)^{\nu}\right]\left(F_{1, \mu, \alpha, \beta, \nu} f\right)\left(\frac{\xi}{a}\right) \times \xi^{-\mu \nu-\alpha}\left(F_{1, \mu, \alpha, \beta, \psi} \psi\right)(\xi) d \xi \text {. }
\end{aligned}
$$

By substituting $\frac{\xi}{a}=x ; d \xi=a d x$, the continuous generalized Hankel-type integral wavelet transform can be written as

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$$
\begin{aligned}
& \left(H_{1, \alpha, \beta, \nu, \mu, \nu,} f\right)(b, a)=a^{-2(\mu \nu \nu-\alpha)-3 \nu} \int_{0}^{\infty} \nu \beta\left(\frac{b}{a}\right)^{-1-2 \alpha+2 \nu}\left(\frac{b \xi}{a}\right)^{\alpha} J_{\mu}\left[\beta\left(\frac{b \xi}{a}\right)^{\nu}\right]\left(F_{1, \mu, \alpha, \beta, \nu} f\right)\left(\frac{\xi}{a}\right) \times \xi^{-\mu \nu-\alpha}\left(F_{1, \mu, \alpha, \beta, \psi}\right)(\xi) d \xi . \\
& =a^{-2(\alpha \nu-\alpha)-3 \nu} \int_{0}^{\infty} \nu \beta\left(\frac{b}{a}\right)^{-1-2 \alpha+2 \nu}(b x)^{\alpha} J_{\mu}\left[\beta(b x)^{\nu}\right]\left(F_{1, \mu, \alpha, \beta, \nu} f\right)(x) \times(a x)^{-\mu \nu-\alpha}\left(F_{1, \mu, \alpha, \beta, \nu} \psi\right)(a x) a d x \\
& =a^{-2(\mu \nu \nu-\alpha)-3 v} a^{-\mu \nu \nu-\alpha+(1-2 \nu+2 \alpha)-1 / 2+1} \int_{0}^{\infty} \nu \beta b^{-1-2 \alpha+2 \nu}(b x)^{\alpha} J_{\mu}\left[\beta(b x)^{\nu}\right]\left(F_{1, \mu, \alpha, \beta, \nu} f\right)(x) x^{-\mu \nu-\alpha}\left(F_{1, \mu, \alpha, \beta, \nu} \psi\right)(a x) d x \\
& =a^{-2(\mu \nu \nu)-3 v} a^{-\mu \nu+\alpha-2 \nu+2} \int_{0}^{3 \infty} \nu \beta b^{-1-2 \alpha+2 \nu}(b x)^{\alpha} J_{\mu}\left[\beta(b x)^{\nu}\right]\left(F_{1, \mu, \alpha, \beta, \nu} f\right)(x) x^{-\mu \nu \nu-\alpha}\left(F_{1, \mu, \alpha, \beta, \nu} \psi\right)(a x) d x . \\
& =a^{-3 \mu \nu+3 \alpha-5 v \nu} \int_{0}^{3 \infty} \nu \beta b^{-1-2 \alpha+2 \nu}(b x)^{\alpha} J_{\mu}\left[\beta(b x)^{\nu}\right]\left(F_{1, \mu, \alpha, \beta, \nu} f\right)(x) x^{-\mu \nu-\alpha}\left(F_{1, \mu, \alpha, \beta, \nu} \psi\right)(a x) d x . \\
& D_{\mu, \alpha, \beta, \nu}(x, y, z)=\int_{0}^{\infty} \xi^{-\mu \nu-\alpha}\left[\begin{array}{l}
\nu \beta x^{-1-2 \alpha+2 \nu}(x \xi)^{\alpha} J_{\mu}\left[\beta(x \xi)^{\nu}\right] \\
\nu \beta y^{-1-2 \alpha+2 \nu}(y \xi)^{\alpha} J_{\mu}\left[\beta(y \xi)^{\nu}\right] \\
\nu \beta z^{-1-2 \alpha+2 \nu}(z \xi)^{\alpha} J_{\mu}\left[\beta(z \xi)^{\nu}\right] d \xi
\end{array}\right] \\
& x=\frac{b}{a} ; y=\frac{t}{a} ; \\
& D_{\mu, \alpha, \beta, \nu}(b / a, t / a, z)=\int_{0}^{\infty} \xi^{-\mu \nu-\alpha}\left[\begin{array}{l}
\nu \beta\left(\frac{b}{a}\right)^{-1-2 \alpha+2 \nu}\left(\frac{b}{a} \xi\right)^{\alpha} J_{\mu}\left[\beta\left(\frac{b}{a} \xi\right)^{\nu}\right] \\
\nu \beta\left(\frac{t}{a}\right)^{-1-2 \alpha+2 \nu}\left(\frac{t}{a} \xi\right)^{\alpha} J_{\mu}\left[\beta\left(\frac{t}{a} \xi\right)^{\nu}\right] \\
\nu \beta z^{-1-2 \alpha+2 \nu}(z \xi)^{\alpha} J_{\mu}\left[\beta(z \xi)^{\nu}\right] d \xi
\end{array}\right] \\
& \xi=a x ; d \xi=a d x . \\
& {\left[\nu \beta\left(\frac{b}{a}\right)^{-1-2 \alpha+2 v}\left(\frac{b}{a} a x\right)^{\alpha} J_{\mu}\left[\beta\left(\frac{b}{a} a x\right)^{\nu}\right]\right]} \\
& D_{\mu, \alpha, \beta, \nu}(b / a, t / a, z)=\int_{0}^{\infty}(a x)^{-\mu \nu-\alpha} \nu \beta\left(\frac{t}{a}\right)^{-1-2 \alpha+2 v}(t x)^{\alpha} J_{\mu}\left[\beta(t x)^{\nu}\right] \\
& \nu \beta z^{-1-2 \alpha+2 v}(z a x)^{\alpha} J_{\mu}\left[\beta(z a x)^{\nu}\right] a d x \\
& D_{\mu, \alpha, \beta, \nu}(b / a, t / a, z)=\int_{0}^{\infty}(a x)^{-\mu \nu-\alpha}\left[\begin{array}{l}
\nu \beta\left(\frac{b}{a}\right)^{-1-2 \alpha+2 v}(b x)^{\alpha} J_{\mu}\left[\beta(b x)^{\nu}\right] \\
\nu \beta\left(\frac{t}{a}\right)^{-1-2 \alpha+2 v}(t x)^{\alpha} J_{\mu}\left[\beta(t x)^{\nu}\right] \\
\nu \beta z^{-1-2 \alpha+2 \nu}(z a x)^{\alpha} J_{\mu}\left[\beta(z a x)^{\nu}\right] a d x
\end{array}\right]
\end{aligned}
$$

## 4. CONCLUSION

The applications of generalized Hankel-type integral wavelet transformation can be applied in signal processing, computer vision, seismology, turbulence, computer graphics, image processing, digital communication, approximation theory, numerical analysis and statistics.

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## Author' biography with Photo

> Dr. V. R. Lakshmi Gorty has overall twenty years service. She is PhD form University of Pune. She has attended many seminars and workshops. She published more than fifty papers at national and international journals and conferences. She has been a resource person for MATLAB in state and national level and visited many colleges with this Performa. She is member of many professional bodies like IAIAM, ISTE, INS and IMS. She is also Congress Member of IAENG. She was the co-chair of ICTSM (International Conference) 2011 held at SVKM's NMIMS University, MPSTME. She worked as an editor of Springer series, where the selected papers of peer reviewed were published. She worked coordinator of the International conference ICATE 2013, sponsored by IEEE X-plore digital library. She is editor of Indian journal of science, engineering \& technology management, approved with an ISSN 0975-525 X, Techno Path (National Journal) since its first issue (vol. I), January 2009.

